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End-to-end deep learning-based framework for path planning and collision checking: bin-picking application – ERRATUM

Mehran Ghafarian Tamizi¹, Homayoun Honari¹, Aleksey Nozdryn-Plotnicki² and Homayoun Najjaran¹

¹University of Victoria, Victoria, BC, V8W 2Y2, Canada

²Apera AI, Vancouver, BC, V6B 2K4, Canada

Corresponding author: Homayoun Najjaran; Email: najjaran@uvic.ca

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